

Electric drive: ROM Series

ROM no longer available



The ROM Series of electric drives from Rotork ensures a low-noise, reliable actuation of various ball valves and butterfly valves. The drives have visual indicators that signal the position of the valve and also contain a manual actuator.

Torque limit switches provide additional protection for the motor. The working range of the servomotor can be set by means of limit switches. As standard the ROM drive is supplied with an anti-condensation heater element and extra limit switches.

The ROM can be supplied with an adaptor for the drive shaft so that it fits the ball valve or butterfly valve (ISO-top) to be actuated.

APPLICATION

Electric drives are used predominantly as a control valve on butterfly valves in automated processes, such as pump and decontamination installations

CHARACTERISTICS

- ✓ Narrow, compact and lightweight induction motors
- ✓ Non-clutch design: direct-acting manual operation
- ✓ 2 extra limit switches
- ✓ Anti-condensation heater element
- ✓ Thermostat
- ✓ Position indicator on the head of the motor
- ✓ ISO-top connection
- ✓ Torque switches and auxiliary switches
- ✓ Electric leadthrough 2x M20 x 1.5p
- ✓ Aluminium powder-coated water and dust-tight housing, IP68
- ✓ ISO 9001, CE standard
- ✓ 1 motor for both 12 - 24 V DC/AC, 50-60 Hz (multi-voltage)
- ✓ Optionally with potentiometer or position transmitter

TECHNICAL DATA

Power supply	: 12 - 24 V DC/AC, 50-60 Hz (multi-voltage)
Maximum temperature	: -30° to +70°C
Relative humidity	: 30% to 95%
Material	: aluminium alloy with powder coating

Mechanical properties

Model	WEIGHT (kg)	Manual	Drive connection (mm)	Basic design (to ISO)
ROM-1	2,2	Level	14	F03/F05
ROM-A	2,8	Level	17	F05/F07
ROM-2	12	Handwheel	22	F07
ROM-3	12	Handwheel	22	F07
ROM-4	26	Handwheel	36	F10
ROM-5	26	Handwheel	36	F10
ROM-6	26	Handwheel	36	F10

Electric performance (24V DC/AC)

Model	Speed (sec/°90)	Torque (Nm)	Max. motor power (W)	Motor speed (rpm)	Max. current consumption run (A)	lock (A)
ROM-1	4,5	8	10	1700	0,6	1,2
	20	35	3,75	1700	0,6	1,2
ROM-A	30	50	3,75	1700	0,6	1,2
ROM-2	17	90	43	1360	1,1	9
ROM-3	22	150	43	1360	1,1	9
	150	150	43	1360	1,1	9
ROM-4	23	400	130	1250	5,5	20
	150	400	130	1250	5,5	20
ROM-5	30	500	130	1250	5,5	20
ROM-6	38	650	130	1250	5,5	20

INSTALLATION & MAINTENANCE

Installation

- ✔ Read the enclosed installation and maintenance instructions before installation.
- ✔ The bottom 2 limit contacts are for opening and closing. The top 2 extra 'vacant' limit contacts 1 and 3 and 2 and 4 are for the connection.
- ✔ The motor has a loose AC printed circuit board that can transform the voltage to DC (the motor is DC).
- ✔ The motor can therefore be connected as an AC or as a DC motor.
- ✔ Ensure correct wiring with respect to voltage and power.
- ✔ Seal the housing and the nut inlet after wiring by means of a matching cable nut or blind plug to prevent the ingress of dust or water and to retain the IP68 protection.
- ✔ Do not install the motor upside down or under the horizontal line.
- ✔ Do not install the motor if there is a possibility of hazardous or explosive gases.
- ✔ The motors are not suitable for continuous operation. Maintain a rest period of at least 2x the running time.
- ✔ If several electric drives have to operate at the same time, these must be connected using separate cables.

Maintenance

- ✔ Switch off the electric power supply before starting maintenance work.

CIRCUIT DIAGRAMS

CIRCUIT IS DRAWN FOR A VALVE IN THE FULLY CLOSED POSITION

ACTUATOR SHOWN IN MID-TRAVEL

12/24V AC/DC SUPPLY

TYPICAL CONTROL - NOT ROTORK SUPPLY

12/24V AC/DC SUPPLY

ACTUATOR SHOWN IN MID-TRAVEL

SINGLE PHASE SUPPLY

ACTUATOR SHOWN IN MID-TRAVEL

THREE PHASE SUPPLY

WIRING FOR ROM1 & ROMA
3 AMP 240VAC MAX.

WIRING FOR ROM2 TO ROM6
5 AMP 240VAC MAX.

DO NOT RUN ACTUATOR TO LIMITS WITH INCORRECT PHASE ROTATION.
WHERE DISTANCES ARE GREAT BETWEEN ACTUATOR AND CONTROL GEAR, CABLE CAPACITANCE MAY CAUSE CONTACTORS TO STICK ON A.C. CIRCUITS

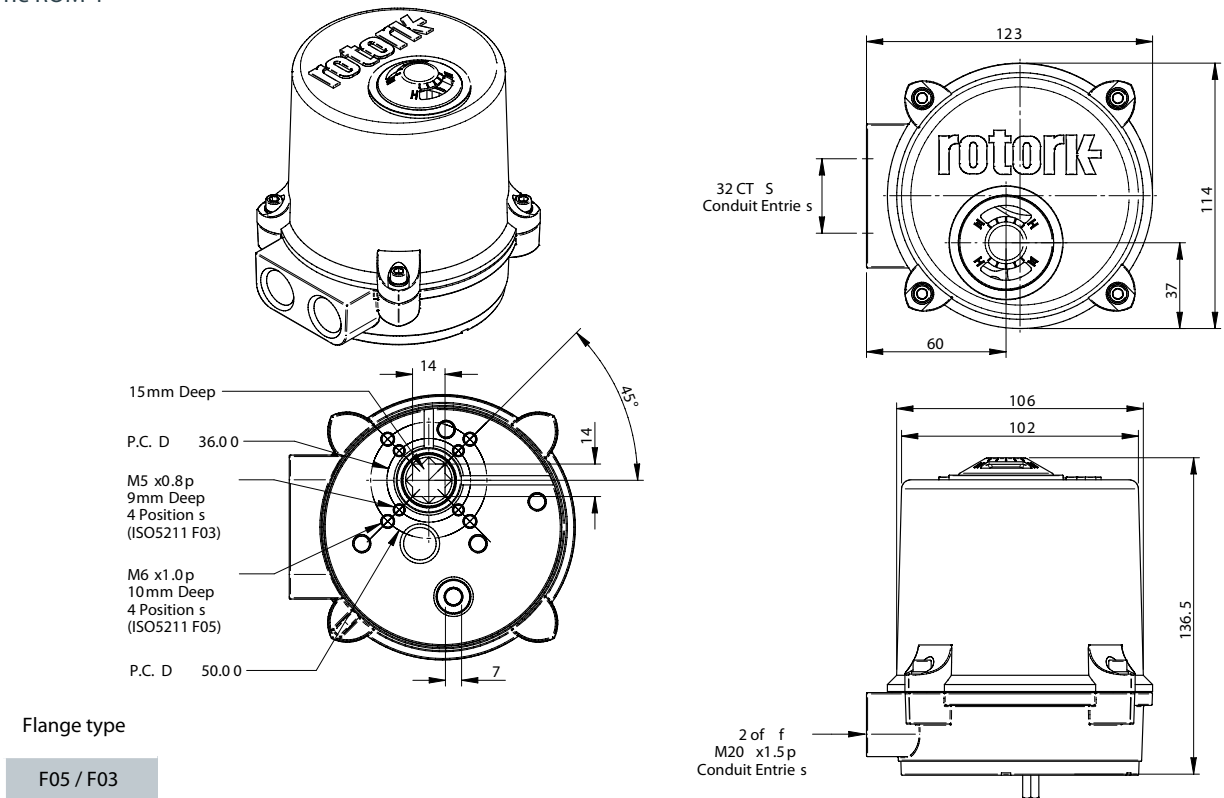
O - OPEN
C - CLOSE
TS - TORQUE SWITCHES
LS - LIMIT SWITCHES
MCB - MINITURE CIRCUIT BREAKER
○ ACTUATOR TERMINAL

CAUTION
SOLID STATE LOGIC SYSTEMS USING ACTUATOR SWITCH SIGNAL INPUTS MUST BE DESIGNED TO PROVIDE A SWITCHING LOAD OF 1 WATT & 24V MINIMUM WITH A TIME CONSTANT NOT LESS THAN 10ms TO MINIMISE SENSITIVITY TO CONTACT VIBRATION.

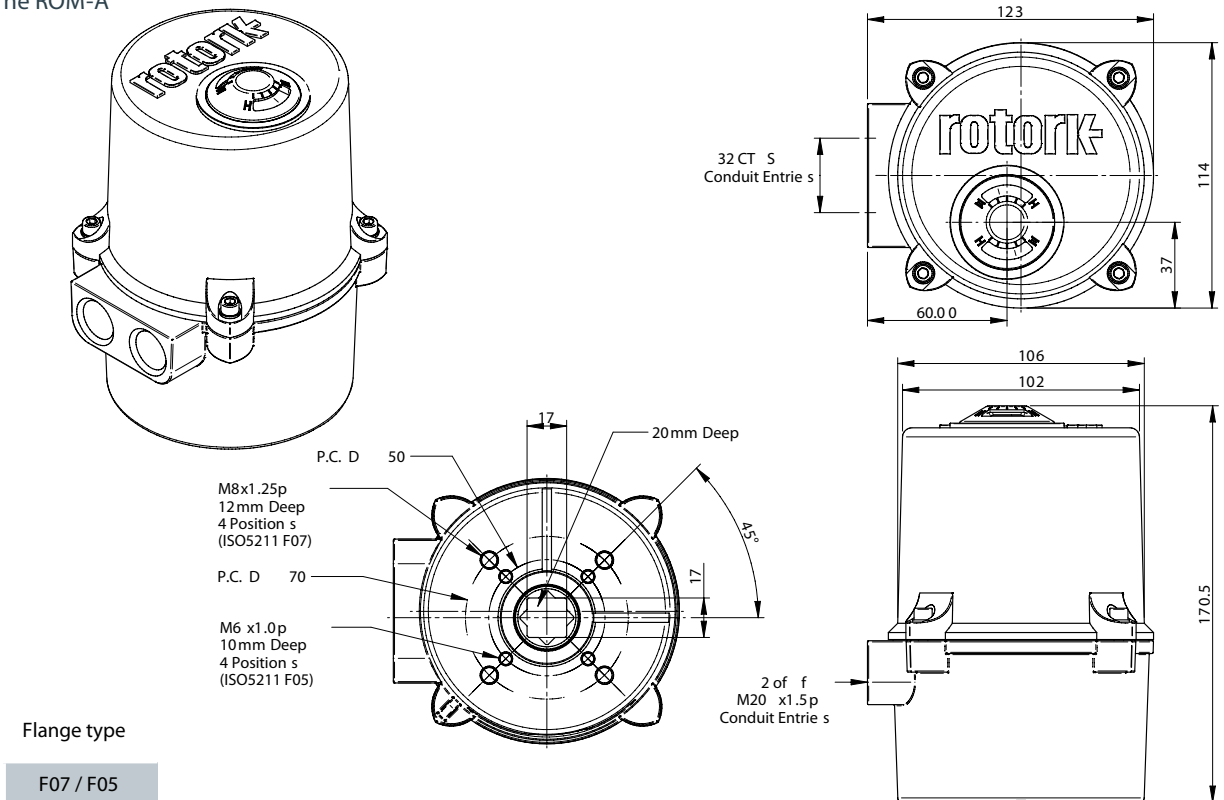
Iss	Date	Chkd	Revision Details	www.rotork.com	BASIC + HEATER + LS3/LS4 -
5	200613 HYE	PJW	Fully open/closed lamp circuit for three phase (5, 6) corrected, 380-440VAC added for HEATER, size updated (A,B,C,D,E,F).	ROTORK CONTROLS LTD BATH, BA1 3JQ ENGLAND Tel:01225-733200	ROTORK CONTROLS INC ROCHESTER NY 14624, USA Tel:585-247-2304
					Drawn by: PJW Date : 170402 Base WD: -- Job No : -- MI No : --
					Circuit Diagram No YS11-00
					Issue No 5

TECHNICAL DRAWINGS I

The ROM-1

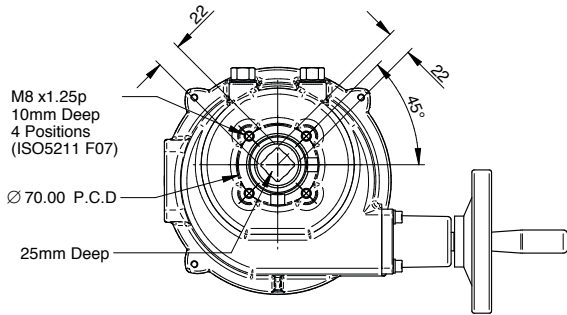
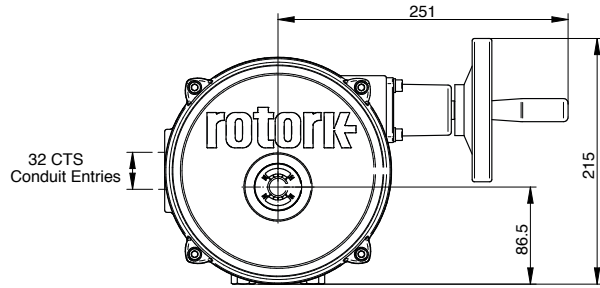
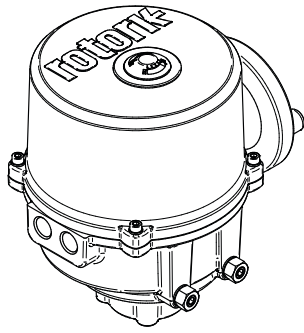


The ROM-A



TECHNICAL DRAWINGS II

The ROM-2/3



M8 x1.25p
10mm Deep
4 Positions
(ISO5211 F07)

Ø 70.00 P.C.D

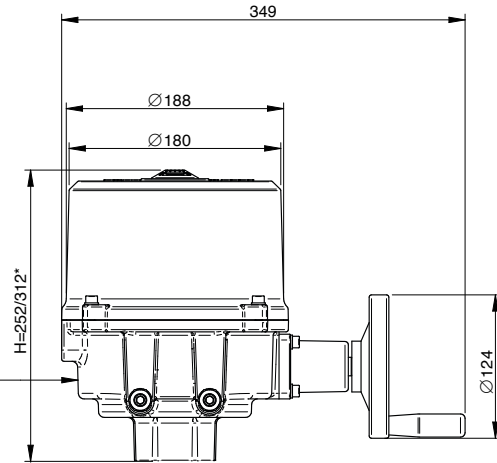
25mm Deep

Flange type

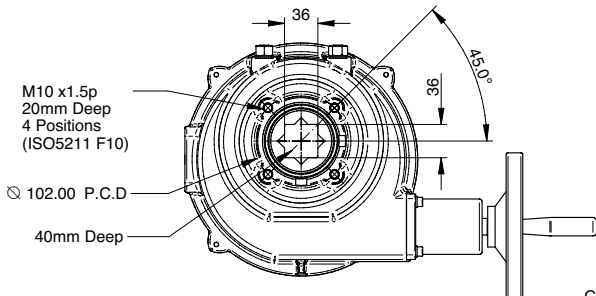
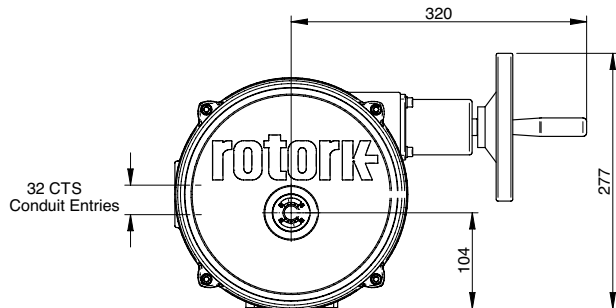
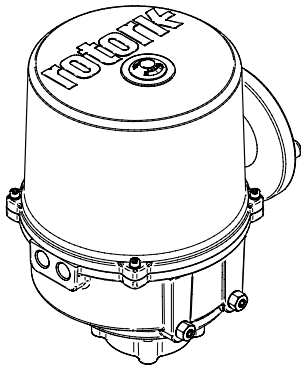
F07

	110 V, 220 V AC 1-Phase	H=252
* ROM-2/3	220 V, 380 V, 440 V AC 3-Phase	H=312
	12 V, 24 V AC/DC	H=312

2 off
M20 x1.5p
Conduit Entries



The ROM-4/5/6



M10 x1.5p
20mm Deep
4 Positions
(ISO5211 F10)

Ø 102.00 P.C.D

40mm Deep

Flange type

F10

2 off
M20 x1.5p
Conduit Entries

